

More dynamics in phase space

- four kinds of generating functions
- transformation to "action-angle" variables

Because phase-space area integrals may be expressed in two equivalent ways

$$\oint_C P dq = \oint_C (-q \cancel{dp}) ,$$

there are four different ways we could have defined our

generating functions:

$$Pdq - PdQ \Big|_t = dF_1 \Big|_t$$

$$-qdp - PdQ_t = dF_2 \Big|_t$$

$$Pdq + QdP \Big|_t = dF_3 \Big|_t$$

$$-qdp + QdP \Big|_t = dF_4 \Big|_t$$

$$F_1 = F_1(q, Q, t) \quad \frac{\partial F_1}{\partial q} = P \quad \frac{\partial F_1}{\partial Q} = -P$$

$$F_2 = F_2(P, Q, t) \quad \frac{\partial F_2}{\partial P} = -q \quad \frac{\partial F_2}{\partial Q} = -P$$

$$F_3 = F_3(P, \underline{P}, t) \quad \frac{\partial F_3}{\partial P} = -q \quad \frac{\partial F_3}{\partial \underline{P}} = Q$$

$$F_4 = F_4(q, \underline{P}, t) \quad \frac{\partial F_4}{\partial q} = P \quad \frac{\partial F_4}{\partial \underline{P}} = Q$$

$$dQ = dQ/t + \frac{\partial Q}{\partial t} dt$$

$$dP = dP/t + \frac{\partial P}{\partial t} dt$$

$$dF_1 = dF_1/t + \left(\underbrace{\frac{\partial F_1}{\partial Q} \frac{\partial Q}{\partial t}}_{-P} + \frac{\partial F_1}{\partial t} \right) dt$$

$$dF_2 = dF_2/t + \left(-P \frac{\partial Q}{\partial t} + \frac{\partial F_2}{\partial t} \right) dt$$

$$dF_3 = dF_3/t + \left(\underbrace{\frac{\partial F_3}{\partial P} \frac{\partial P}{\partial t}}_{+Q} + \frac{\partial F_3}{\partial t} \right) dt$$

$$dF_4 = dF_4/t + \left(Q \frac{\partial P}{\partial t} + \frac{\partial F_4}{\partial t} \right) dt$$

$$pdq = P(dQ - \cancel{\frac{\partial Q}{\partial t} dt})$$

$$+ dF_1 + \cancel{P \frac{\partial Q}{\partial t} dt} - \frac{\partial F_1}{\partial t} dt$$

(3)

$$-qdp = P \left(dQ - \frac{\partial Q}{\partial t} dt \right) + dF_2$$

$$+ \cancel{P \frac{\partial Q}{\partial t} dt} - \frac{\partial F_2}{\partial t} dt$$

$$pdq = -Q \left(dP - \frac{\partial P}{\partial t} dt \right) + dF_3$$

$$-Q \cancel{\frac{\partial P}{\partial t} dt} - \frac{\partial F_3}{\partial t} dt$$

$$-qdp = -Q \left(dP - \frac{\partial P}{\partial t} dt \right) + dF_4$$

$$-Q \cancel{\frac{\partial P}{\partial t} dt} - \frac{\partial F_4}{\partial t} dt$$

We see that in all four cases
 the form of the action is un-
 changed provided the Hamiltonian
 is transformed as

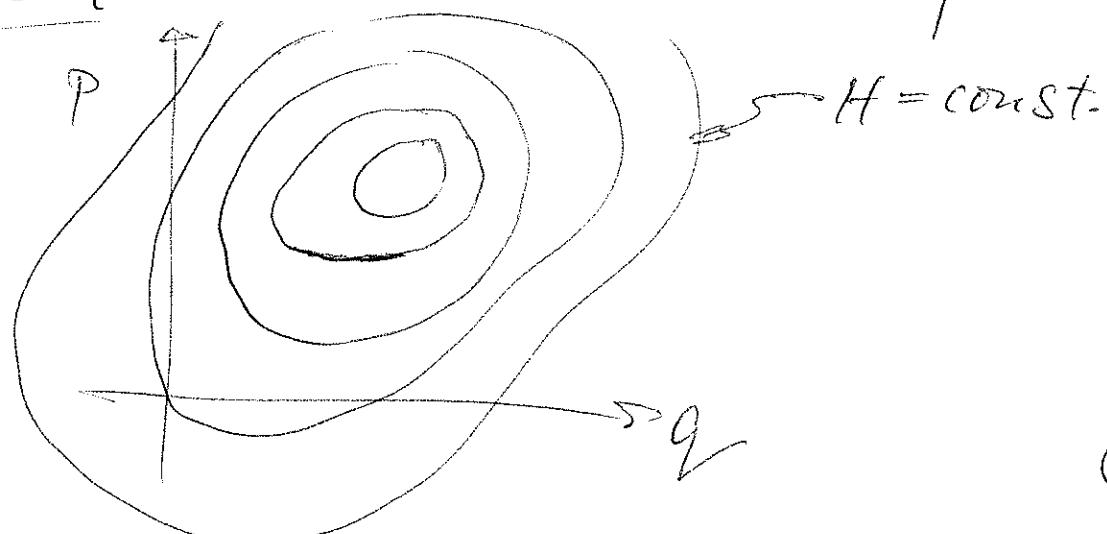
(4)

$$H'(Q, P, t) = H(Q(P, t), P(Q, P, t), t)$$

$$+ \frac{\partial F}{\partial t}$$

Where F is F_1, F_2, F_3 , or F_4 .

There is a special choice of phase-space variables that we use for periodic motion. Since the motion follows $H = \text{constant}$ contours (for ~~one~~ 1 degree of freedom the energy "surface" is just a curve), the contours will be closed when the motion is periodic.



(5)

We now define the "action" variable like this:

$$I(q, p) = \frac{\text{phase-space area enclosed by contour that passes through } q, p}{2\pi}$$

I will play the role of the new momentum variable, previously denoted P . By construction, the Hamiltonian is purely a function of I :

$$H = h(I)$$

The new coordinate variable, that I is "conjugate to", will be called Θ instead of Q . Hamilton's eq'n's

written in terms of the new variables are exceedingly simple:

$$\dot{\theta} = \frac{\partial H}{\partial I} = h'(I)$$

$$\dot{I} = -\frac{\partial H}{\partial \theta} = 0$$

The second equation tells us $I=I_0=\text{constant}$ (something we already knew from $H=h(I)=\text{const.}$).

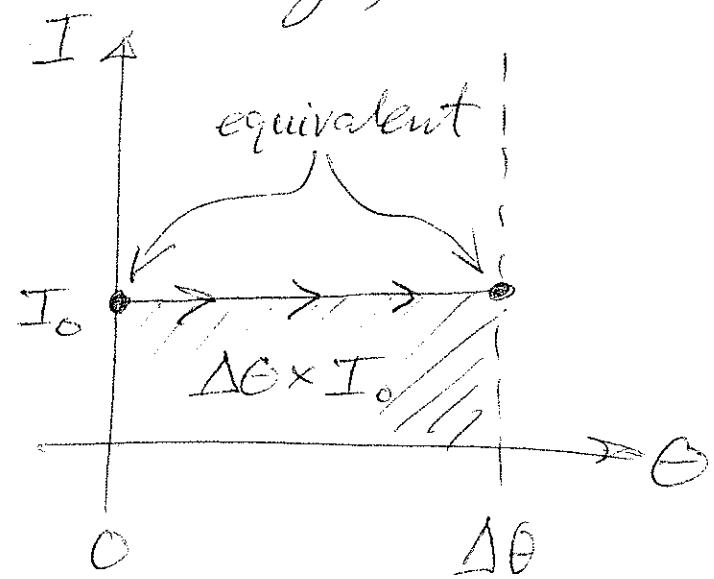
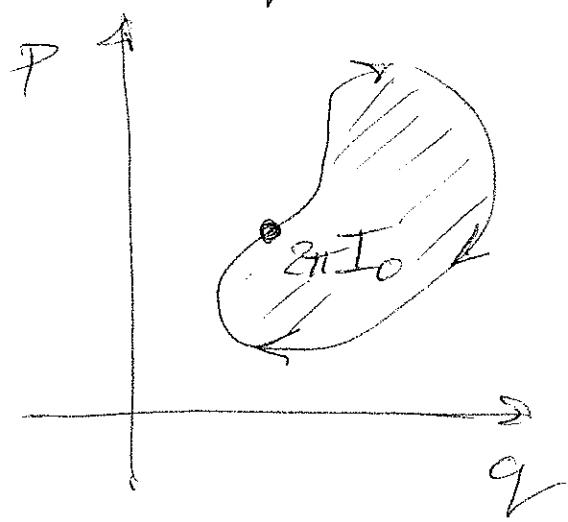
The first equation is almost as simple:

$$\dot{\theta} = h'(I_0) = \omega_0 = \text{const.}$$

$$\Rightarrow \theta(t) = \omega_0 t + \theta_0$$

The construction of the (θ, I) phase space has periodicity of

of the orbits built into its topology by identifying points as equivalent when θ is changed by a fixed amount $\Delta\theta$. The correct value of $\Delta\theta$ follows from our definition of I and the fact that the transformation is canonical (phase-space area preserving).



$$\Rightarrow \Delta\theta = 2\pi$$

Because of the identified points in the θ - I plane, the orbit is actually

closed, and the area enclosed is as indicated in the sketch.

Now if T is the period of the orbit for some I_0 , then our solution to Hamilton's equations tells us

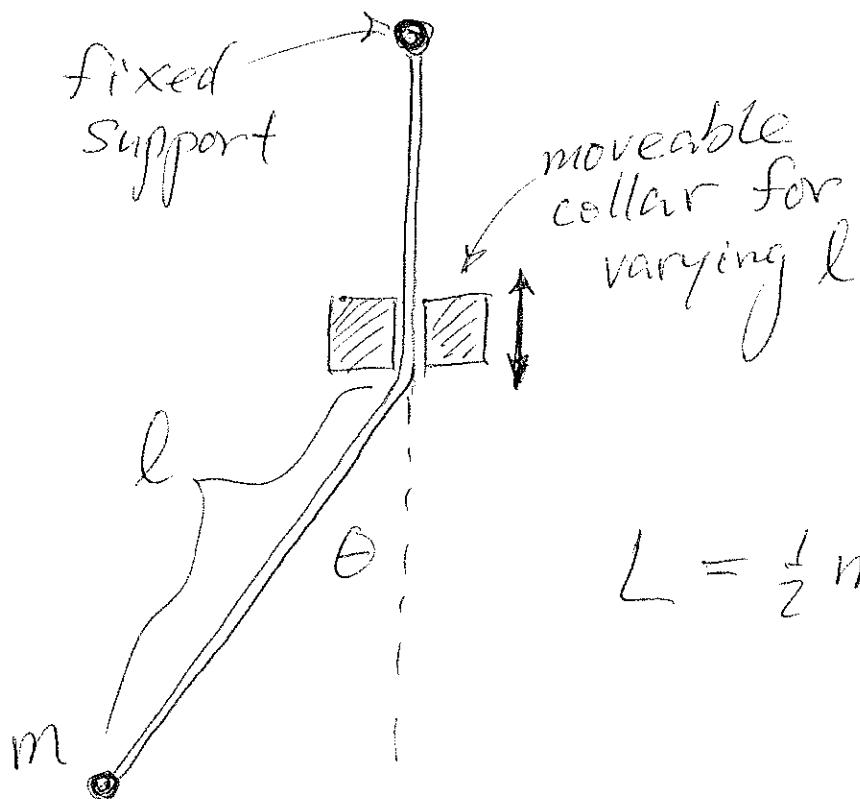
$$\omega_0 T = 2\pi,$$

so
$$h'(I_0) = \frac{2\pi}{T},$$

in other words : the derivative of the energy (H) with respect to action ($2\pi I$) is the inverse of the orbit period.

Let's apply the transformation to action-angle variables to the

simplest model of periodic motion,
the harmonic oscillator. In
particular, we will study a
pendulum whose string passes
through a collar that enables us
to vary the length of the string:



$$L = \frac{1}{2} m(l\dot{\theta})^2 - mg l(1 - \cos\theta)$$

$\approx \frac{1}{2} \theta^2$

$\theta \rightarrow q$ (so as not to
confuse with ~~an~~
action-angle Θ)

$$P = \frac{\partial L}{\partial \dot{q}} = ml^2 \dot{q}$$

$$H = \dot{P}\dot{q} - L = \frac{\dot{P}^2}{2ml^2} + \frac{1}{2}mglq^2$$

define $w = \sqrt{g/l}$

$$H = \frac{\dot{P}^2}{2ml^2} + \frac{1}{2}mw^2l^2q^2$$

Here is a generating function for the transformation to action-angle variables:

$$F(q, \theta) = \frac{1}{2}mw.l^2q^2\cot\theta$$

(previously, $\theta = Q$). Here are the two equations satisfied by F :

$$\dot{P} = \frac{\partial F}{\partial q} = mw.l^2q\cot\theta$$

$$\dot{I} = -\frac{\partial F}{\partial \theta} = -\frac{1}{2}mw.l^2q^2\left(\frac{-1}{\sin^2\theta}\right)$$

Solving for q in the second equation:

$$q = \sqrt{\frac{2I}{m\omega^2}} \sin \theta$$

Substituting this into the first equation:

$$P = \sqrt{2I m\omega^2} \cos \theta$$

Finally:

$$H = \frac{2I m\omega^2}{2m\ell^2} \cos^2 \theta + \frac{1}{2} \frac{m\omega^2 \ell^2 I}{m\omega^2} \sin^2 \theta$$

$$= \omega I.$$

We see that the harmonic oscillator is especially simple, in the sense that $h(I) = \omega I$, $h'(I) = \omega = \frac{2\pi}{T}$.